

Tracking Protocol Description

This document describes the messages stream produced by the glideradar_master daemon that receives the data from the various stations and processes it in a more useful format.

AMQP message format

AMQP messages from the glideradar_master dameon are sent to the ygg.glideradar.processed_messages topic exchange.

Every AMQP message has a type header that specifies the message type.

The payload is JSON-encoded and the contents are type-specific.

Bayeux message format

The Bayeux interface is accessible at the URI

http(s)://tracker.acao.it/faye

The client should subscribe to the /glideradar/processed/** channel.

The general structure of all the messages is the following:

```
{
  type: "<TYPE>",
  payload: Object,
  timestamp: "2015-06-24T16:48:30.000+02:00"
}
```

 $There \ are \ several \ message \ types, for \ each \ type \ \textit{payload} \ contains \ the \ encapsulated \ data \ whose \ structure \ is \ type-specific.$

TRAFFICS UPDATE

"payload" contains an object with the following attributes:

```
{
  stations: Object,
  traffics: Object
}
```

Both stations and objects should be treated as associative arrays.

Stations

stations contains updates for all the active stations, every attribute (key) is the station identifier defined by us.

This is an example of a station object:

```
alt: 240.1,
cog: 0,
flarm_code: null,
gps_fix_qual: 1,
gps_fix_type: 3,
gps_hdop: 1.34,
gps_pdop: 2.9,
gps_sats: 7,
gps_vdop: 2.57,
last_update: "2015-06-24T14:50:31.000Z",
lat: 45.808027666666667,
lng: 8.7722363333333334,
name: "ACAO",
sog: 0.013,
}
```

```
alt
                    Altitude in meters
cog
                    Course-Over-Ground in degrees
flarm code
                    FLARM identifier. Null if not available.
icao_code
                    ICAO identifier. Null if not available.
gps_fix_qual
                    GPS Fix quality
gps_fix_type
                    GPS Fix type (0,1=Not available, 2=2D, 3=3D)
gps_hdop
                    GPS Horizontal dispersion
gpd_pdop
                    GPS Position dispersion
                    Number of GPS sats active
gps_sats
gps_vdop
                    GPS Vertical dispersion
last_update
                    Last update received this station
                    Latitude in decimal degrees. Positive values for N, negative values for S
lat
                    Longitude in decimal degrees. Positive values for E, negative for W
lng
name
                    Station identifier, equal to the key
                    Speed Over Ground in m/s
sog
```

Traffics

traffics contains updates for all the object for which an update has been received within the last 1-second frame. *traffics* attributes (keys) are an unique, opaque, identifier for the specific traffic.

This is an example of a traffic entry:

```
{
  alt: 238.1,
  cog: 0,
  cr: 0.1,
  last_update: "2015-06-24T14:50:30.000Z",
  lat: 45.809054001026,
  lng: 8.770054324061164,
  plane_id: 1851,
  sog: 0,
  tr: 0,
  type: 1,
}
```

alt Altitude in meters

cog Course-Over-Ground in degrees

Climb rate in m/s cr

Climb rate in m/s

last_update

Last update received for the specified traffic

Latitude in decimal degrees. Positive values for N, negative values for S

Longitude in decimal degrees. Positive values for E, negative for W

plane_id

Plane identifier, equal to the key

sog

Speed Over Ground in m/s

Turn rate in °/s

Traffic type according to ELARM specified types

type Traffic type according to FLARM specified types

TRAFFIC NEW

```
{
  plane_id: 3906,
  plane_info: {
    common_radio_frequency: "128.450",
    flarm_code: "DF0860",
    flarm_id: "flarm:DF0860",
    home_airport: "LILC",
    icao_code: null,
    owner_name: "ACAO",
    plane_id: 3906,
    race_registration: "",
    registration: "I-IVWP",
    type: 1,
    type_id: 56,
    type_name: "Schleicher ASK-21",
},
    text: "New traffic I-IVWP (DF0860), type 1",
}
```

This message is sent when new traffic is showing up as a convenience for the tracking visualizer. The information in *plane_info* comes from FlarmNet and an internal database which has higher priority.

If the tracking visualizer is started after TRAFFIC_NEW was sent the same data can be obtained with an HTTP request to http(s)://tracker.acao.it/ygg/planes/<id> with an Accept: application/json header or the .json extension appended to the URI.

TRAFFIC_ALIVE

```
{
    since: "2015-06-24T15:01:36.000Z",
    text: "Traffic MOBIL1 (DF0853) Not alive",
}
```

Traffic that is still active but whose signal has been lost is alive again. Since contains the timestamp when the traffic has been lost.

TRAFFIC_LOST

```
{
  text: "Traffic MOBIL1 (DF0853) Reception lost",
}
```

Traffic data was not received for 10 seconds so it is now considered lost.

TRAFFIC_REMOVED

```
{
  text: "Traffic D-2155 (DF0879) removed",
}
```

Traffic data was not received for several minutes so it was removed from the list of active traffics.

STATION_ONLINE

```
{
    since: "2015-06-24T15:01:36.000Z",
    sta_id: "ACAO",
    sta: {
        alt: 238.7,
        cog: 0,
        flarm_code: null,
        gps_fix_qual: 1,
        gps_fix_type: 3,
        gps_hdop: 0.94,
        gps_pdop: 1.64,
        gps_sats: 9,
        gps_vdop: 1.34,
        last_update: "2015-06-24T15:01:43.000Z",
        lat: 45.80802883333333,
        lng: 8.7722475,
        name: "ACAO",
        sog: 0.037,
    },
    text: "Station ACAO Now online",
}
```

A new station is online.

STATION_OFFLINE

A station went offline.

LAND

```
{
  text: "Traffic D-KMOS (DD8ECC) Landed",
}
```

A landing has been detected.

TAKEOFF

```
{
   text: "Traffic D-KMOS (DD8ECC) Takeoff",
}
```

A takeoff has been detected.

TOW_STARTED

```
{
  text: "Traffic I-EIAG (DD8ECC) tow started with D-1234 (DD1234)",
  towing: {
    traffic: Object,
    alt: 340.5,
    cog: 278,
    cr: 4.5,
    last_update: "2015-06-24T15:24:18.000Z",
    lat: 45.80918566781867,
    lng: 8.77411480499005,
    plane_id: 4052,
    sog: 34.2,
    tr: 0,
    type: 1,
},
}
```

A tow has been detected. The towed glider's data is included in the message.

TOW_ANOMALY

```
{
  text: "Traffic I-EIAG (DD8ECC) tow detected in tow_released. Missed landing?",
}
```

The tow detection heuristic has detected an abnormal condition.

TOW_RELEASED

```
{
  text: "Traffic I-EIAG (DD8ECC) Tow released",
  duration: 355,
  towing: {
    traffic: Object,
    alt: 1256.5,
    cog: 332,
    cr: 2.5,
    last_update: "2015-06-24T15:24:18.000Z",
    lat: 45.80918566781867,
    lng: 8.77411480499005,
    plane_id: 4052,
    sog: 43.2,
    tr: 0,
    type: 1,
  },
}
```

The tow detection heuristic has detected a release.